



A kinetic approach in modeling compact Siegbahn molecular drag stages: physical and numerical aspects 64th IUVSTA Workshop on Practical Applications and Methods of Gas Dynamics for Vacuum Science and Technology

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## Outline

- Introduction: Statement of the problem and typical approaches
- The starting point: Sharipov's Holwek model
- Extension to Siegbhan stages
- A rough approximation:
  - Theory
  - Results
- A consistent approach:
  - Theory
- Conclusions and open questions



## Statement of the problem

- Need for a computational model for Siegbahn drag pumps that takes into account: • Transitional rarefied flow regime

  - Curved channels (spiral grooves)
  - Clearances
- •The pumping effect is due to a circumferential velocity induced by the rotor motion: • It develops a 3D flow along the channel

  - It imposes a pressure jump
- Presence of inertial forces:
  - Centrifugal force
  - Coriolis force









## **Typical approaches**

The flow properties (flow rates and stresses), in the limit of its stationary solution, could be computed by means of various modeling approaches:

- Fully 3D approaches
  - Direct Simulation Monte Carlo DSMC (J.Heo, Y. Hwang, J. Vac . Sci. Technol. A 20, 2002)
  - Kinetic Boltzmann equation
- Reduced order approaches based on the kinetic equation (linearized 2D Boltzmann equation)
  - Asymptotic diffusion models spiral channel section (K.Aoki, P.Degond, L. Mieussens et al., Multiscale Model. Simul. 6, 2008)
  - Sharipov's Holweck model drag channel section (*F. Sharipov, P.Fahrenbach, A.Zipp J. Vac . Sci. Technol. A* 23, 2005)

Purpose of **extending** Sharipov's approach for Holweck pumps to radial pumps in Siegbahn geometry.



# Summary of Sharipov's Holweck model (I)

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- Flow field is characterized by two distinct phenomena:
  - Flow field due to the rotation of the cylinder wall -> Couette
  - II. Flow field due to the pressure gradient -> Poiseuille
- Flow field decoupled in two distinct directions:
  - The main flow direction along the channel (z direction)
  - The leak flow across the channel and over the groove's tip (x direction)



•The main flow is expressed as the superposition of those elemental solutions, while no inertial effects, no curvature of the channel and no end effects are taken into account



α

×

u<sup>x</sup><sub>rot</sub>

 $u_{rot}^{z}$ 

α

u.

<u>ð</u>n

## Summary of Sharipov's Holweck model (II)

- In the local 2D cross section of the channel, the following assumptions are made:
  - Elemental flow are calculated from the stationary Boltzmann equation linearized in the rotational velocity and pressure gradients components, according to the elemental flow in exam.

$$\mathbf{v} \cdot \boldsymbol{\nabla} f = \frac{P}{\mu} \left( f_M - f \right)$$

- BGK closure for the collisional term (isothermal flows)
- The order of equation (3D) is reduced assuming that derivatives along the channel direction (z-coordinate) are locally zero (Couette Flow ) or constant (Poiseuille Flow).
- Flow is determined in the cross section of the channel, and it is dependent only on the local rarefaction parameter  $\delta = hP/\mu v_0$ , considered as constant in the section (linearization).
- Mass conservation is locally enforced to obtain a value of pressure gradient consistent with the applied forces and boundary conditions.



# Siegbahn stages modeling concepts

- Siegbahn stages are mainly characterized by a flow
  - in the direction tangential to the spiral channel (rotation of the disk)
  - in the direction **normal** to the channel (**pressure gradients**)
- In general, the same considerations made for the Holweck pump could be applied, if an **appropriate** reference system is chosen
  - cylindrical, non-inertial reference system

$$c_r \frac{\partial f}{\partial r} + c_\phi \frac{\partial f}{r \partial \phi} + c_y \frac{\partial f}{\partial y} + \frac{c_\phi^2}{r} \frac{\partial f}{\partial c_r} - \frac{c_r c_\phi}{r} \frac{\partial f}{\partial c_\phi} = \delta \left[ M(f) - f \right]$$

- . Inertial effects are **automatically** included
- Constraints in the choice of the computational channel section (constant tangential velocity and periodicity circumference arc).



# Siegbahn stages : a rough approximation(I)

We roughly applied the same approach of the Holweck model, with the same decomposition in 4 elemental flows provided that:

 Geometry of the channel section is expressed in the global reference system of the pump in cylindrical coordinates

- Linearized governing equations are solved in the local reference system of cartesian, fixed, coordinates defined by the spiral geometry in the channel centerline (inertial forces does not appear explicitly)
- •Let x,y,z be the local reference system (green) and  $\phi$ ,y,r the global reference system (red) :

$$c_x \frac{\partial f}{\partial x} + c_y \frac{\partial f}{\partial y} + \delta f = \delta f^M + g, \quad dx = r\cos(\theta) d\Phi$$

• The two system are rotated between each other of an angle  $\theta$ , (defined by the spiral geometry, variable with the radial and tangential coordinates of the global system). The function g is the residual of the linearization (equal to 0 in Couette flows, equal to  $c_x$  or  $c_z$  in Poiseuille flows)



local reference system (cartesian) - governing equations FIXED

reference section -

computational grid

system (cylindrical) -

ROTATING

pump parameters

# Siegbahn stages : a rough approximation (II)



- Pressure evolution along the spiral channel can be still obtained enforcing local mass conservation
- A variable geometry for the section is set along the channel. Thus, a coupled computation of Boltzmann equation and pressure ODE is required, in order to march along the channel section by section
- In first approximation, we impose standard Maxwell diffuse scattering boundary conditions on walls, and zero gradient to clearances
- . No wall impermeability and periodicity are provided



# Siegbahn stages : Results (I)

Hydrogen



- Max error on  $K_{max} < 10\%$
- Max error on  $P_{in}$  < 10%

Φ <sub>0</sub>	R <sub>in</sub>	R <sub>disk</sub>	h	e	N	ω	Flow
[°deg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	Dir.
90	23	51.5	3	0.3	12	963	CP



# Siegbahn stages : Results (II)

Nitrogen



- Max error on K<sub>max</sub> ≈ 50%
- Max error on  $P_{in} \approx 35\%$

Φ <sub>0</sub>	R <sub>in</sub>	R <sub>disk</sub>	h	e	N	ω	Flow
[°deg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	Dir.
90	23	51.5	3	0.3	12	963	



# Siegbahn stages : Results (III)



- H2, max error on K  $\approx$  50%
- N2, max error on K ≈ 30%
- Unable to predict the forline tolerance

Φ <sub>0</sub>	R <sub>in</sub>	R <sub>disk</sub>	h	e	N	ω	Flow
[°deg]	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	Dir.
360	23	51.5	1.5	0.3	4	963	CP



## Siegbahn stages : a consistent approach

- The former method is not accurate when
  - . Curvature of the spiral channel is high
  - Heavy gases are considered (not negligible inertial effects and linear approximation questionable)
- A more consistent approach will be to solve the governing equation in cylindrical

$$c_r \frac{\partial f}{\partial r} + c_\phi \frac{\partial f}{r \partial \phi} + c_y \frac{\partial f}{\partial y} + \frac{c_\phi^2}{r} \frac{\partial f}{\partial c_r} - \frac{c_r c_\phi}{r} \frac{\partial f}{\partial c_\phi} = \delta \left[ M(f) - f \right]$$

• In particular, the scalar product  $\mathbf{c} \cdot \nabla f$  is expressed in a general curvilinear, non orthogonal, system of coordinates (S,T,y) as described in figure:



$$c_r \frac{\partial f}{\partial r} + c_\phi \frac{\partial f}{r \partial \phi} + c_y \frac{\partial f}{\partial y} = c^S \frac{\partial f}{\partial S} + c^T \frac{\partial f}{\partial T} + c^y \frac{\partial f}{\partial y}$$

- In this new configuration, impermeability on walls and periodicity on clearances are easily recovered.
- Holweck-like approximations are imposed on the S-derivative.



### Conclusions

- The prediction of the flow field in a radial drag pump with Siegbhan geometry hs been investigated
- An extension of the Sharipov's Holwek model has been proposed
- In a first approximation, a straigthforward application of the linearized 2D Boltzmann Eq. in cartesian coordinates has been employed
- The results are promising, but not sufficiently accurate, possibly due to non consistent boundary conditions
- A more accurate model, with consistent boundary conditions, is under development



#### **Open questions**

 Is there any possibility to correct the results for heavier gases, which are more sensitive to the linearization?

 What are the limits of the 2D approach? What are the benefits of a 3D approach? How much does a 3D approach increase the computational cost?



## A possible approach?

- 1) Use the 3D non-linear equation
- 2) Approximate the derivative of the distribution function in the main direction by the derivative of the equilibrium
- 3) Use one-sided derivatives (maybe unstable) for the discretization of this derivative
- 4) Space marching "section-by-section" from inlet to outlet



#### **Flow results: Couette Flow**

# HIGH RAREFACTION $\delta = 0.003$

LOW RAREFACTION  $\delta = 25$ 



All results obtained for a hydrogen gas



#### **Flow results: Couette Flow**



All results obtained for a hydrogen gas



#### **Flow results: Poiseuille Flow**

# HIGH RAREFACTION $\delta = 0.003$

# $LOW RAREFACTION \\ \delta = 25$



#### All results obtained for a hydrogen gas



#### **Flow results: Poiseuille Flow**



All results obtained for a hydrogen gas



## **Details on numerical scheme (newest approach)**

- A Discrete Velocity Method, with a finite difference scheme (upwind) is used to integrate the linearized Boltzmann equations
- Derivatives in the velocity space are treated with a modified upwind scheme (T-UNCE), as suggested by Mieussens (*J.Comp Phys 2000*)
- The three-dimensional velocity space (cr,cθ,cy) is rearranged in cylindrical coordinates (cm,Ψ,cy), with a typical dimension of 16x40x16 degrees of freedom.
- Integrals for macroscopic quantities are evaluated using a Gauss-Hermite (cy-velocities) and Gauss Legendre (cm-velocities) quadrature formulas.
- Stationary solutions are captured through a pseudo-transient technique (relaxation of the time-dependent linearized BGK-Boltzmann equation up to its stationary solution)
- An explicit time-marching scheme is employed. The solver is designed to work on MPI architectures to speed up calculations.

